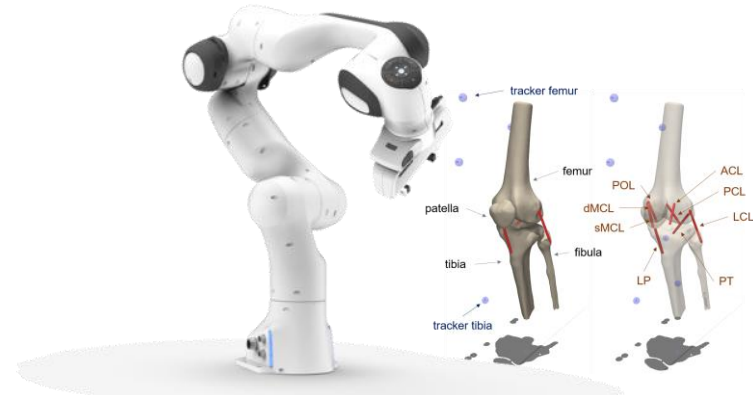


Execution and Evaluation of a Robotic Experiment to Determine the Parameters of a Human Cadaveric Knee Joint using a Franka Emika Robot

Required steps:

- Planning the Experiment
- Understanding the Franka ROS
- Acquire the Systems to collect valuable Data (like Force-Torque, Position and Orientation)
- Execution of the Experiment
- Documentation and Evaluation



Prerequisites:

- Basic Python 
- Learn the Franka Panda ROS
- Basic knowledge about biomechanics